

Optimal Discovery  
with Probabilistic Expert Advice  
[JMLR - arXiv:1110.5447]

Sébastien Bubeck, Damien Ernst and Aurélien Garivier

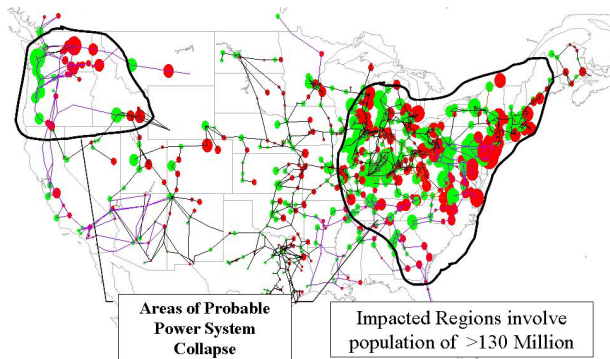
January 12th, 2016

# Outline

- 1 Presentation of the model
- 2 The Good-UCB algorithm
- 3 Optimality results

# The problem

## Power system security assessment

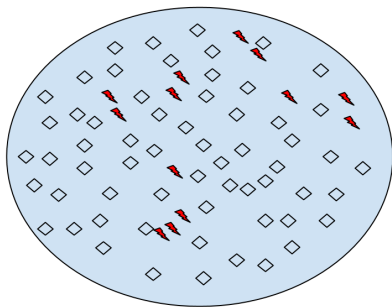


By Mark MacAlester, Federal Emergency Management Agency [Public domain], via Wikimedia Commons

**Identifying contingencies/scenarios** that could lead to unacceptable operating conditions (dangerous contingencies) if no preventive actions were taken.

# The model

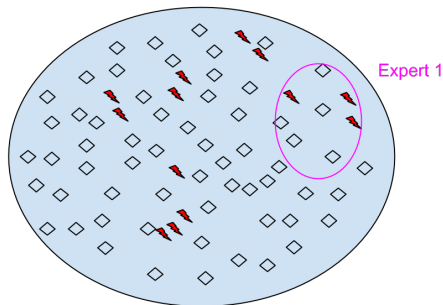
- Subset  $A \subset \mathcal{X}$  of important items
- $|\mathcal{X}| \gg 1$ ,  $|A| \ll |\mathcal{X}|$
- Access to  $\mathcal{X}$  only by probabilistic experts  $(P_i)_{1 \leq i \leq K}$  : sequential independent draws



**Goal : discover rapidly the elements of  $A$**

# The model

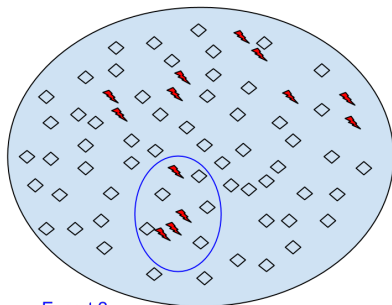
- Subset  $A \subset \mathcal{X}$  of important items
- $|\mathcal{X}| \gg 1$ ,  $|A| \ll |\mathcal{X}|$
- Access to  $\mathcal{X}$  only by probabilistic experts  $(P_i)_{1 \leq i \leq K}$  : sequential independent draws



**Goal : discover rapidly the elements of  $A$**

# The model

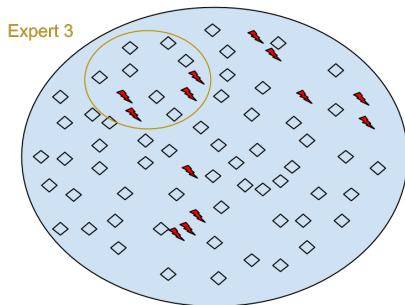
- Subset  $A \subset \mathcal{X}$  of important items
- $|\mathcal{X}| \gg 1$ ,  $|A| \ll |\mathcal{X}|$
- Access to  $\mathcal{X}$  only by probabilistic experts  $(P_i)_{1 \leq i \leq K}$  : sequential independent draws



**Goal : discover rapidly the elements of  $A$**

# The model

- Subset  $A \subset \mathcal{X}$  of important items
- $|\mathcal{X}| \gg 1$ ,  $|A| \ll |\mathcal{X}|$
- Access to  $\mathcal{X}$  only by probabilistic experts  $(P_i)_{1 \leq i \leq K}$  : sequential independent draws



**Goal : discover rapidly the elements of  $A$**

## Goal

At each time step  $t = 1, 2, \dots$  :

- pick an index  $I_t = \pi_t(I_1, Y_1, \dots, I_{s-1}, Y_{s-1}) \in \{1, \dots, K\}$  according to past observations
- observe  $Y_t = X_{I_t, n_{I_t, t}} \sim P_{I_t}$ , where

$$n_{i,t} = \sum_{s \leq t} \mathbb{1}\{I_s = i\}$$

**Goal** : design the strategy  $\pi = (\pi_t)_t$  so as to **maximize the number of important items found** after  $t$  requests

$$F^\pi(t) = \left| A \cap \{Y_1, \dots, Y_t\} \right|$$

**Assumption** : non-intersecting supports

$$A \cap \text{supp}(P_i) \cap \text{supp}(P_j) = \emptyset \text{ for } i \neq j$$



# Is it a Bandit Problem ?

It looks like a bandit problem. . .

- sequential choices among  $K$  options
- want to maximize cumulative rewards
- exploration vs exploitation dilemma

. . . but it is **not a bandit problem!**

- rewards are not i.i.d.
- **destructive rewards** : no interest to observe twice the same important item
- all strategies eventually equivalent

## The oracle strategy

**Proposition :** Under the non-intersecting support hypothesis, the greedy oracle strategy

$$I_t^* \in \arg \max_{1 \leq i \leq K} P_i(A \setminus \{Y_1, \dots, Y_t\})$$

is optimal : for every possible strategy  $\pi$ ,  $\mathbb{E}[F^\pi(t)] \leq \mathbb{E}[F^*(t)]$ .

**Remark :** the proposition is false if the supports may intersect

$\implies$  estimate the “**missing mass of important items**” !

# Outline

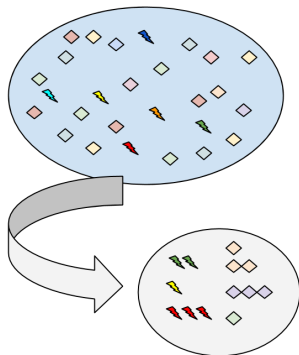
- 1 Presentation of the model
- 2 The Good-UCB algorithm**
- 3 Optimality results

## Missing mass estimation

Let us first focus on one expert  $i : P = P_i, X_n = X_{i,n}$

$X_1, \dots, X_n$  independent draws of  $P$

$$O_n(x) = \sum_{m=1}^n \mathbb{1}\{X_m = x\}$$



How to 'estimate' the **total mass of the *unseen*** important items

$$R_n = \sum_{x \in A} P(x) \mathbb{1}\{O_n(x) = 0\} ?$$

## The Good-Turing Estimator

Idea : use the **hapaxes** = items seen only once (linguistic)

$$\hat{R}_n = \frac{U_n}{n}, \quad \text{where } U_n = \sum_{x \in A} \mathbb{1}\{O_n(x) = 1\}$$

**Lemma [Good '53]** : For every distribution  $P$ ,

$$0 \leq \mathbb{E}[\hat{R}_n] - \mathbb{E}[R_n] \leq \frac{1}{n}$$

**Proposition** : With probability at least  $1 - \delta$  for every  $P$ ,

$$\hat{R}_n - \frac{1}{n} - (1 + \sqrt{2})\sqrt{\frac{\log(4/\delta)}{n}} \leq R_n \leq \hat{R}_n + (1 + \sqrt{2})\sqrt{\frac{\log(4/\delta)}{n}}$$

See [McAllester and Schapire '00, McAllester and Ortiz '03] :

- deviations of  $\hat{R}_n$  : McDiarmid's inequality
- deviations of  $R_n$  : negative association

# The Good-UCB algorithm

Estimator of the missing important mass for expert  $i$  :

$$\hat{R}_{i,n_i,t-1} = \frac{1}{n_{i,t-1}} \sum_{x \in A} \mathbb{1} \left\{ \sum_{s=1}^{n_{i,t-1}} \mathbb{1}\{X_{i,s} = x\} = 1 \right.$$

$$\left. \text{and } \sum_{j=1}^K \sum_{s=1}^{n_{j,t-1}} \mathbb{1}\{X_{j,s} = x\} = 1 \right\}$$

**Good-UCB algorithm :**

- 1: For  $1 \leq t \leq K$  choose  $I_t = t$ .
- 2: **for**  $t \geq K + 1$  **do**
- 3:   Choose  $I_t = \arg \max_{1 \leq i \leq K} \left\{ \hat{R}_{i,n_i,t-1} + C \sqrt{\frac{\log(4t)}{n_{i,t-1}}} \right\}$
- 4:   Observe  $Y_t$  distributed as  $P_{I_t}$
- 5:   Update the missing mass estimates accordingly
- 6: **end for**

# Outline

- 1 Presentation of the model
- 2 The Good-UCB algorithm
- 3 Optimality results**

# Classical analysis

**Theorem :** For any  $t \geq 1$ , under the non-intersecting support assumption, Good-UCB (with constant  $C = (1 + \sqrt{2})\sqrt{3}$ ) satisfies

$$\mathbb{E} [F^*(t) - F^{UCB}(t)] \leq 17\sqrt{Kt \log(t)} + 20\sqrt{Kt} + K + K \log(t/K)$$

Remark : Usual result for bandit problem, but not-so-simple analysis



## Sketch of proof

- 1 On a set  $\tilde{\Omega}$  of probability at least  $1 - \sqrt{\frac{K}{t}}$ , the “confidence intervals” hold true simultaneously all  $u \geq \sqrt{Kt}$
- 2 Let  $\bar{I}_u = \arg \max_{1 \leq i \leq K} R_{i, n_{i, u-1}}$ . On  $\tilde{\Omega}$ ,

$$R_{I_u, n_{I_u, u-1}} \geq R_{\bar{I}_u, n_{\bar{I}_u, u-1}} - \frac{1}{n_{I_u, u-1}} - 2(1 + \sqrt{2}) \sqrt{\frac{3 \log(4u)}{n_{I_u, u-1}}}$$

- 3 But one shows that  $\mathbb{E}F^*(t) \leq \sum_{u=1}^t \mathbb{E}R_{\bar{I}_u, n_{\bar{I}_u, u-1}}^\pi$
- 4 Thus

$$\begin{aligned} & \mathbb{E} [F^*(t) - F^{UCB}(t)] \\ & \leq \sqrt{Kt} + \mathbb{E} \left[ \sum_{u=1}^t \frac{1}{n_{I_u, u-1}} + 2(1 + \sqrt{2}) \sqrt{\frac{3 \log(4t)}{n_{I_u, u-1}}} \right] \\ & \leq \sqrt{Kt} + K + K \log(t/K) + 4(1 + \sqrt{2}) \sqrt{3Kt \log(4t)} \end{aligned}$$

# Experiment : restoring property

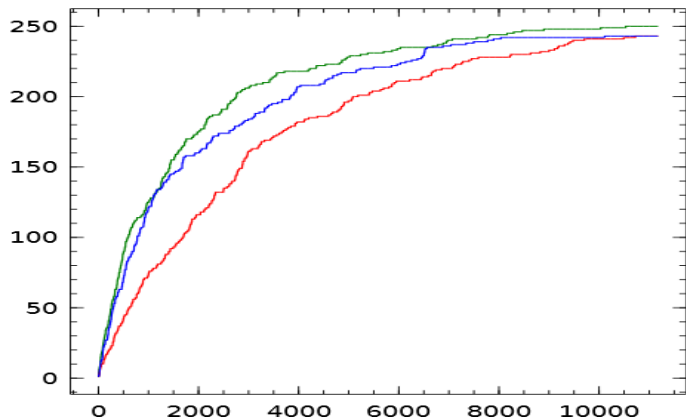


FIGURE – green : oracle, blue : Good-UCB, red : uniform sampling

## Another analysis of Good-UCB

For  $\lambda \in (0, 1)$ ,  $T(\lambda)$  = time at which missing mass of important items is smaller than  $\lambda$  on all experts :

$$T(\lambda) = \inf \left\{ t : \forall i \in \{1, \dots, K\}, P_i(A \setminus \{Y_1, \dots, Y_t\}) \leq \lambda \right\}$$

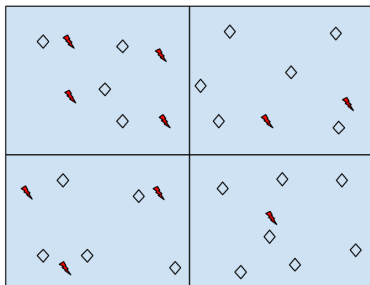
**Theorem :** Let  $c > 0$  and  $S \geq 1$ . Under the non-intersecting support assumption, for Good-UCB with  $C = (1 + \sqrt{2})\sqrt{c+2}$ , with probability at least  $1 - \frac{K}{cS^c}$ , for any  $\lambda \in (0, 1)$ ,

$$T_{UCB}(\lambda) \leq T^* + KS \log(8T^* + 16KS \log(KS)),$$

$$\text{where } T^* = T^* \left( \lambda - \frac{3}{S} - 2(1 + \sqrt{2})\sqrt{\frac{c+2}{S}} \right)$$

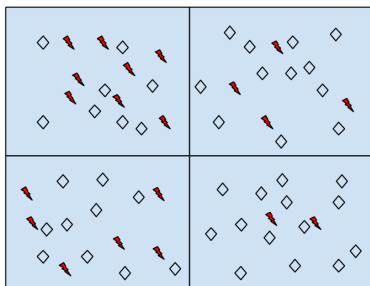
# The macroscopic limit

- Restricted framework :  $P_i = \mathcal{U}\{1, \dots, N\}$
- $N \rightarrow \infty$
- $|A \cap \text{supp}(P_i)|/N \rightarrow q_i \in (0, 1)$ ,  $q = \sum_i q_i$



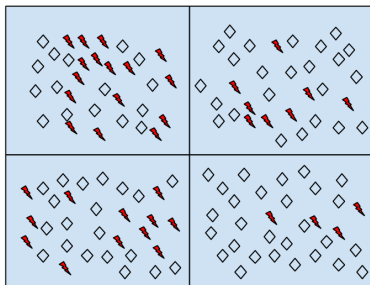
# The macroscopic limit

- Restricted framework :  $P_i = \mathcal{U}\{1, \dots, N\}$
- $N \rightarrow \infty$
- $|A \cap \text{supp}(P_i)|/N \rightarrow q_i \in (0, 1)$ ,  $q = \sum_i q_i$



# The macroscopic limit

- Restricted framework :  $P_i = \mathcal{U}\{1, \dots, N\}$
- $N \rightarrow \infty$
- $|A \cap \text{supp}(P_i)|/N \rightarrow q_i \in (0, 1)$ ,  $q = \sum_i q_i$



## The Oracle behaviour

The limiting discovery process of the Oracle strategy is *deterministic*

**Proposition :** For every  $\lambda \in (0, q_1)$ , for every sequence  $(\lambda^N)_N$  converging to  $\lambda$  as  $N$  goes to infinity, almost surely

$$\lim_{N \rightarrow \infty} \frac{T_*^N(\lambda^N)}{N} = \sum_i \left( \log \frac{q_i}{\lambda} \right)_+$$

## Oracle vs. uniform sampling

**Oracle :** The proportion of important items not found after  $Nt$  draws tends to

$$q - F^*(t) = I(t) \underline{q}_{I(t)} \exp(-t/I(t)) \leq K \underline{q}_K \exp(-t/K)$$

with  $\underline{q}_K = \left( \prod_{i=1}^K q_i \right)^{1/K}$  the geometric mean of the  $(q_i)_i$ .

**Uniform :** The proportion of important items not found after  $Nt$  draws tends to  $K \bar{q}_K \exp(-t/K)$

$\implies$  Asymptotic ratio of efficiency

$$\rho(q) = \frac{\bar{q}_K}{\underline{q}_K} = \frac{\frac{1}{K} \sum_{i=1}^k q_i}{\left( \prod_{i=1}^k q_i \right)^{1/K}} \geq 1$$

larger if the  $(q_i)_i$  are unbalanced



## Macroscopic optimality

**Theorem :** Take  $C = (1 + \sqrt{2})\sqrt{c + 2}$  with  $c > 3/2$  in the Good-UCB algorithm.

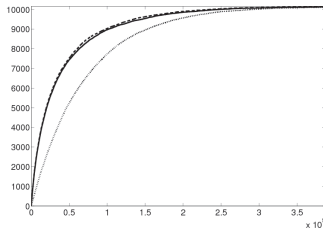
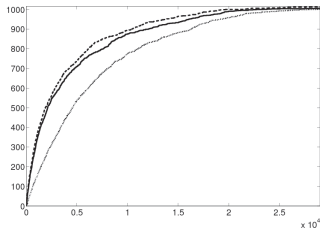
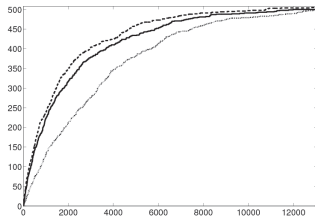
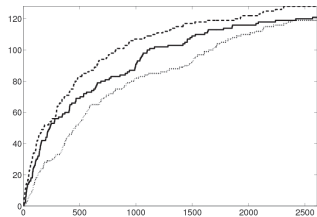
- For every sequence  $(\lambda^N)_N$  converging to  $\lambda$  as  $N$  goes to infinity, almost surely

$$\limsup_{N \rightarrow +\infty} \frac{T_{UCB}^N(\lambda^N)}{N} \leq \sum_i \left( \log \frac{q_i}{\lambda} \right)_+$$

- The proportion of items found after  $Nt$  steps  $F^{GUCB}$  converges *uniformly* to  $F^*$  as  $N$  goes to infinity

# Experiment

Number of items found by Good-UCB (solid), the OCL (dashed), and uniform sampling (dotted) as a function of time for sizes  $N = 128$ ,  $N = 500$ ,  $N = 1000$  and  $N = 10000$  in a 7-experts setting.



## Conclusion and perspectives

- We propose an algorithm for the optimal discovery with probabilistic expert advice
- We give a standard regret analysis under the only assumption that the supports of the experts are non-overlapping
- We propose a different optimality result, which permits a macroscopic analysis in the uniform case
- Another interesting limit to consider is when the number of important items to find is fixed, but the total number of items tends to infinity (Poisson regime)
- Then, the behavior of the algorithm is not very good : too large confidence bonus because no tight deviations bounds for the Good-Turing estimator when the proportion of important items tends to 0