

# Spin Battery Operated by Ferromagnetic Resonance

Arne Brataas

Department of Physics

Norwegian University of  
Science and Technology



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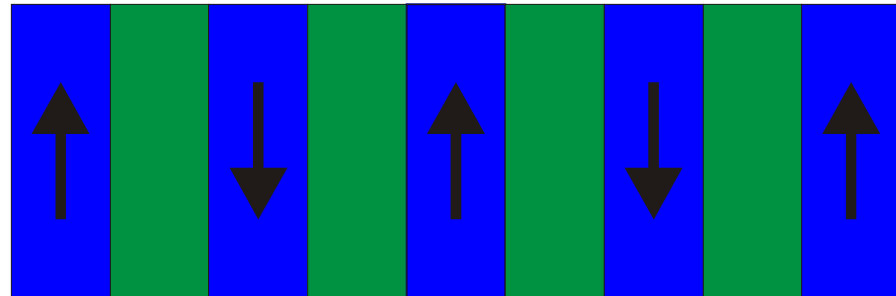
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*Collaboration:*

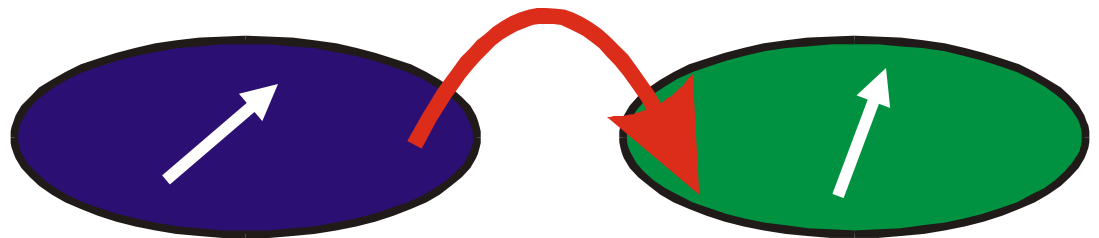
*Gerrit E. W. Bauer, Bertrand I. Halperin, Yaroslav Tserkovnyak.*

# Magneto-electronics

Giant magnetoresistance  
(GMR)



Tunnel magnetoresistance  
(TMR)

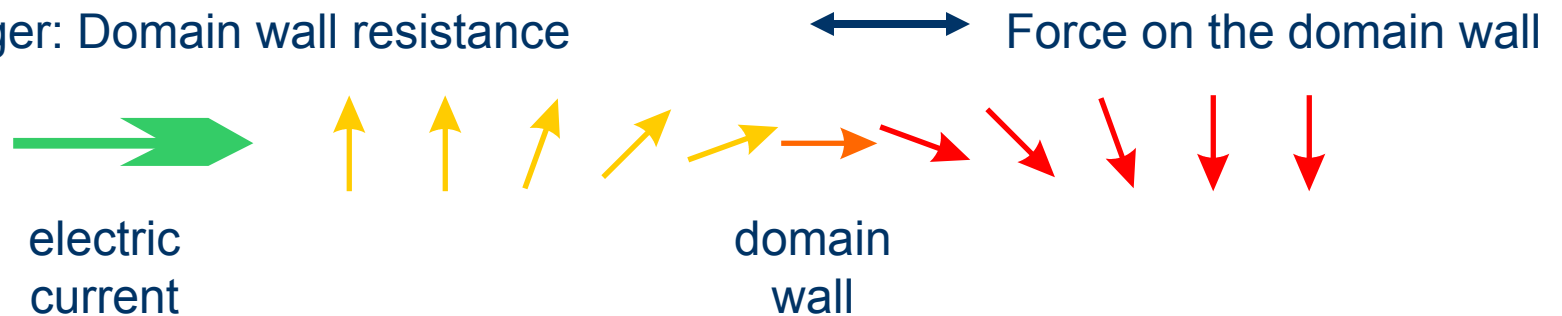


SAN JOSE, Calif., Nov. 10, 1997: IBM today announced the world's highest capacity desktop PC disk drive with new breakthrough technology called "Giant Magnetoresistive (GMR)" heads.

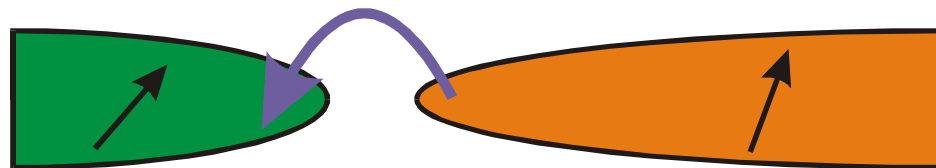
# Spin Torque

*Cause and effect, Newton's third law:*

L. Berger: Domain wall resistance



J. Slonczewski: Discrete system, tunnel contact.

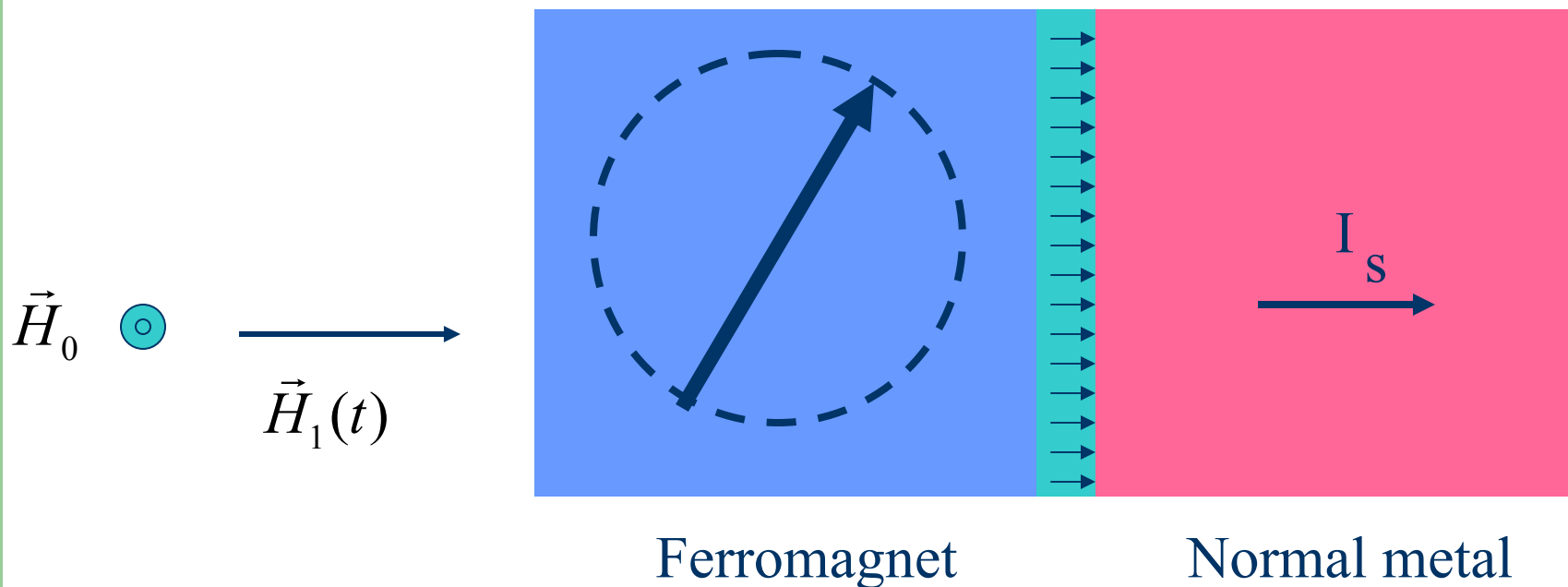


# Ferromagnetic Resonance

Rotating magnetization direction:  $\vec{m}(t)$

Static magnetic field:  $\vec{H}_0$

Rotating magnetic field:  $\vec{H}_1(t)$



# Spin Pumping: Abrupt Change

Population of spin-up and spin-down bands in equilibrium:



Abruptly reverse the magnetization direction:



# Scattering Matrix Approach

$$\hat{S}_{nm} = \begin{pmatrix} \hat{r}_{nm} & \hat{t}_{nm} \\ \hat{t}'_{nm} & \hat{r}'_{nm} \end{pmatrix}$$

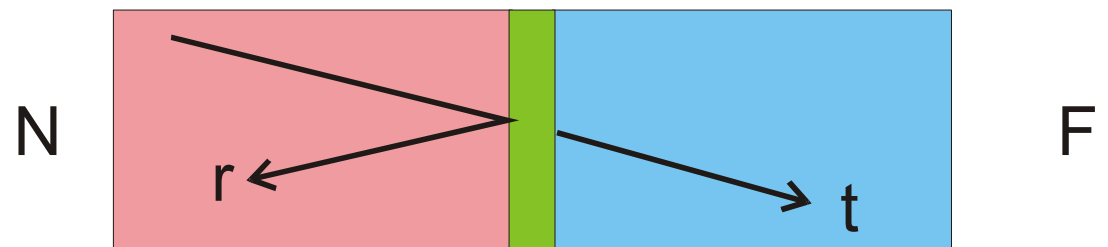
No spin-flip:

$$\hat{S} = S^\uparrow \hat{u}^\uparrow + S^\downarrow \hat{u}^\downarrow$$

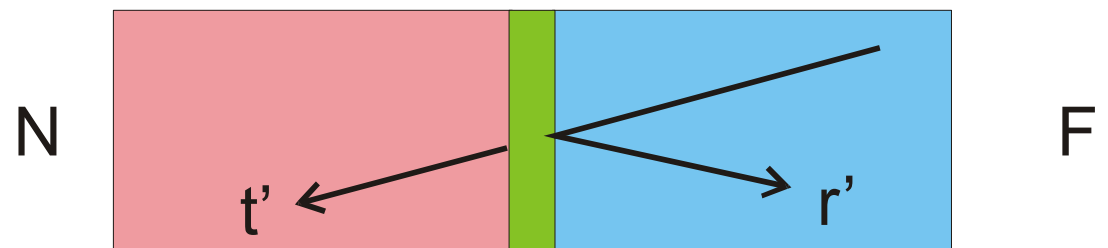
$$\hat{u}^\uparrow = (1 + \vec{\sigma} \cdot \vec{m}) / 2$$

$$\hat{u}^\downarrow = (1 - \vec{\sigma} \cdot \vec{m}) / 2$$

Incoming wave: Normal metal



Incoming wave: Ferromagnet



# Adiabatic Spin Pump

2x2 current due to adiabatic change of parameter  $X(t)$

$$\hat{I}^{PUMP}(t) = e \frac{\partial \hat{n}}{\partial X} \frac{dX(t)}{dt}$$

The emissivity is

$$\frac{\partial \hat{n}}{\partial X} = \frac{1}{4\pi i} \sum_{mn,J} \left( \frac{\partial \hat{S}_{mn,NJ}}{\partial X} \hat{S}_{mn,NJ} - \hat{S}_{mn,NJ} \frac{\partial \hat{S}_{mn,NJ}}{\partial X} \right)$$

There is no pumping of charge. The spin-current is

$$\vec{I}_s^{PUMP} = \frac{\hbar}{4\pi} (A_r + A_i \vec{m} \times) \left( \vec{m} \times \frac{d\vec{m}}{dt} \right)$$

$$A_r = \frac{1}{2} \sum_{nm} \left[ \left| r_{nm}^{\uparrow} - r_{nm}^{\downarrow} \right|^2 + \left| t_{nm}^{\uparrow} - t_{nm}^{\downarrow} \right|^2 \right]$$

$$A_i = \text{Im} \sum_{nm} \left[ r_{nm}^{\uparrow} \left( r_{nm}^{\downarrow} \right)^* + t_{nm}^{\uparrow} \left( t_{nm}^{\downarrow} \right)^* \right]$$



# Spin Pumping

*Magnetization precession induces spin-current into normal metal*

1) No spin-dissipation in the normal metal

*Spin accumulation, spin-injection, spin-battery*

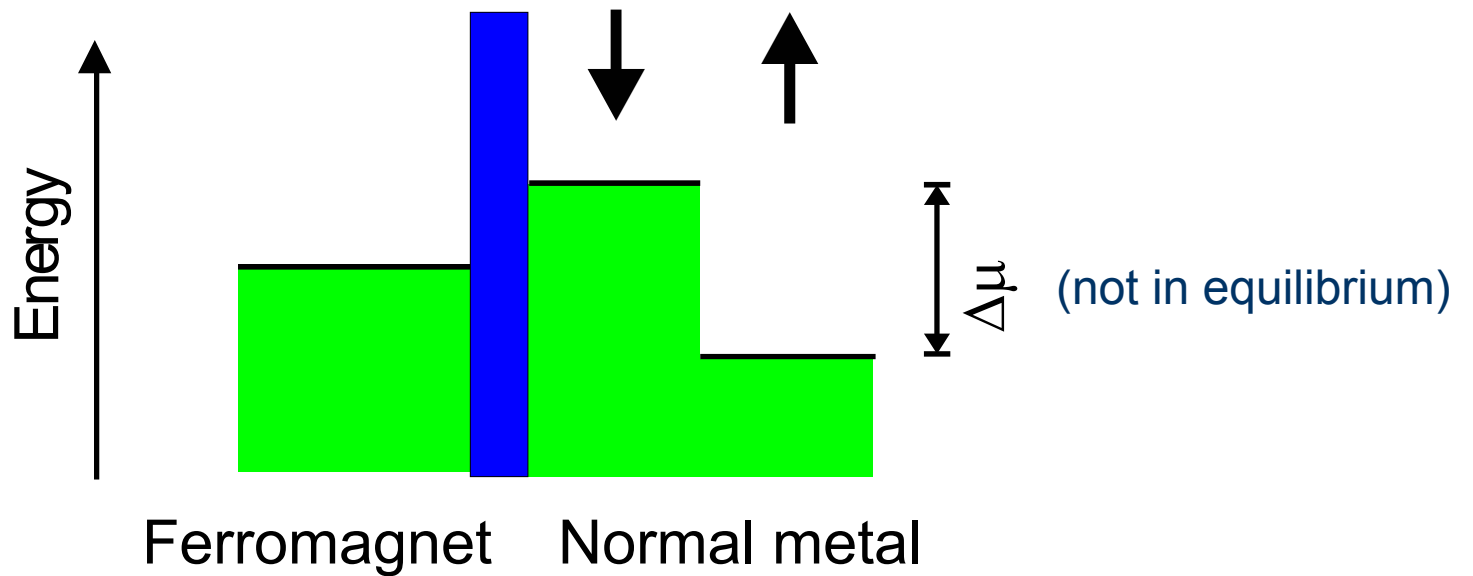
2) Perfect spin-dissipation when the spins relax in the normal metal

*Enhanced Gilbert damping in Ferromagnet*

# Spin Accumulation

$$s = N \Delta\mu$$

$N$  Density of states



# Source Current and Back Flow

Diffusion contribution and time-dependent contribution:

$$\vec{I}_s = \vec{I}_s^{\text{source}} - \vec{I}_s^{\text{back}}$$

Constant magnetization:

$$\vec{I} = -\vec{I}_s^{\text{back}}, \quad \vec{I}^{\text{source}} = 0$$

↑  
Diffusion process

No non-equilibrium occupation:

$$\vec{I}_s = \vec{I}_s^{\text{source}}, \quad \vec{I}_s^{\text{back}} = 0$$

↑  
Adiabatic spin pumping

# Boundary Condition for Spin Flow

Transport regime:

Ferromagnet larger than the ferromagnetic coherence length.

Ferromagnet smaller than longitudinal spin-flip relaxation length.

Spin pumping:

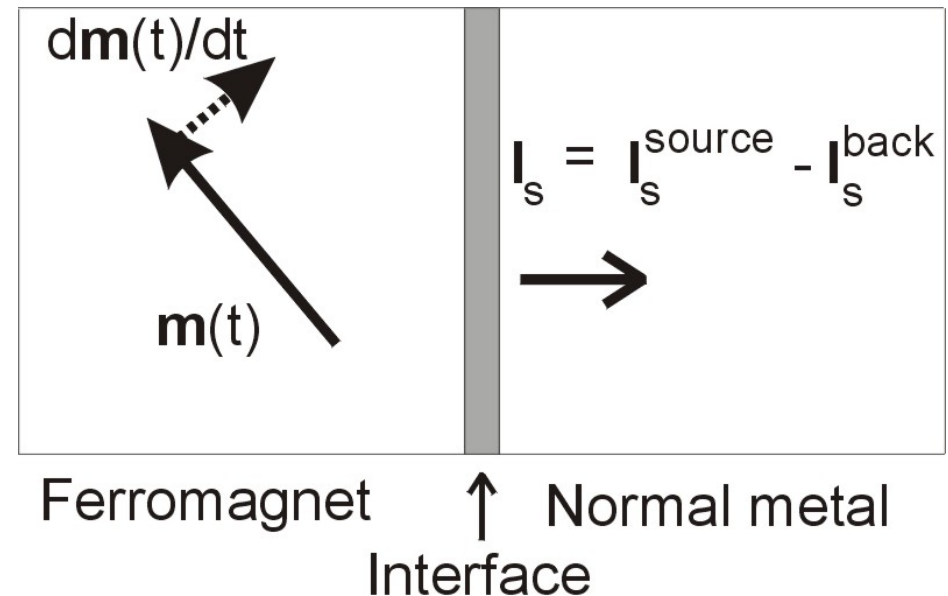
$$\vec{I}_s^{\text{source}} = \frac{\hbar}{4\pi} g_{\uparrow\downarrow} \vec{m} \times \frac{d\vec{m}}{dt}$$

Backflow [PRL **84**, 2481 (2000)]:

$$\vec{I}_s^{\text{back}} = \frac{g_{\uparrow\downarrow}}{2\pi N} \left[ \vec{s} - \vec{m} (\vec{m} \cdot \vec{s}) \right]$$

Mixing conductance

$$g_{\uparrow\downarrow} = \sum_{nm} \left[ \delta_{nm} - r_{nm}^{\uparrow} \left( r_{nm}^{\downarrow} \right)^* \right]$$



# Spin Diffusion in Normal Metal

$$\frac{\partial \vec{s}}{\partial t} = D \frac{\partial^2 \vec{s}}{\partial x^2} - \frac{\vec{s}}{\tau_s}$$

Boundary condition at F-N interface:  $\left( DA\hbar \frac{\partial \vec{s}}{\partial x} \right)_{x=0} = \vec{I}_s = \vec{I}_s^{\text{source}} - \vec{I}_s^{\text{back}}$

Boundary condition at the end of the sample:  $\left( DA\hbar \frac{\partial \vec{s}}{\partial x} \right)_{x=L} = 0$

Spin bias:  $\Delta \vec{\mu} = \frac{2\vec{s}}{N}$

The spin-current and the accompanying spin-bias have AC and DC components.

# Spin Battery

The frequency harmonics of the spin bias are strongly suppressed when

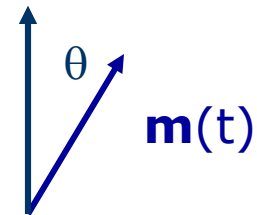
$$l_s (\omega \tau_s)^{-1/2} < L < l_s$$

which is satisfied when

$$\tau_s > \omega \sim 10^{-11} \text{ s} / H_0(T)$$

The spin-bias is then:

$$\langle \Delta \vec{\mu} \rangle_t = \hbar \omega \frac{\sin^2 \theta}{\sin^2 \theta + \gamma}$$



$\theta$ : FMR precession cone angle

$\omega$ : cyclotron frequency

# Spin Bias

Reduction factor:  $\gamma = \frac{\tau_i}{\tau_s} \frac{\tanh(L/l_s)}{L/l_s}$

Spin-injection rate:  $\tau_i^{-1} = \frac{g_{\uparrow\downarrow}}{2\pi\hbar NAL}$

Large systems have a smaller injection rate since more states have to be filled.

Metallic contact: The mixing conductance is

$$g_{\uparrow\downarrow} = \kappa \frac{Ak_F^2}{4\pi}, \quad \kappa \sim 1$$

$$\frac{\tau_i}{\tau_s} = \sqrt{\frac{8}{3}} \frac{1}{\kappa} \sqrt{\varepsilon} \frac{L}{l_s}, \quad \varepsilon = \frac{\tau}{\tau_s}$$

# Spin Bias

$$\langle \Delta \vec{\mu} \rangle_t = \hbar \omega \frac{\sin^2 \theta}{\sin^2 \theta + \gamma}$$

The maximum spin bias is realized when  $L \gg l_s$  ( $\gamma \rightarrow 0$ ):

$$\langle \Delta \vec{\mu} \rangle_t = \hbar \omega$$

Typical resonance frequencies ( $H_0 = 1.0 \text{ T}$ ):  $\hbar \omega \approx 0.1 \text{ meV}$

Example:  $L/l_s = 10$  gives  $\theta > 6$  degrees.

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Al:  $l_s \sim 1 \mu\text{m}$

Cu:  $l_s \sim 1 \mu\text{m}$

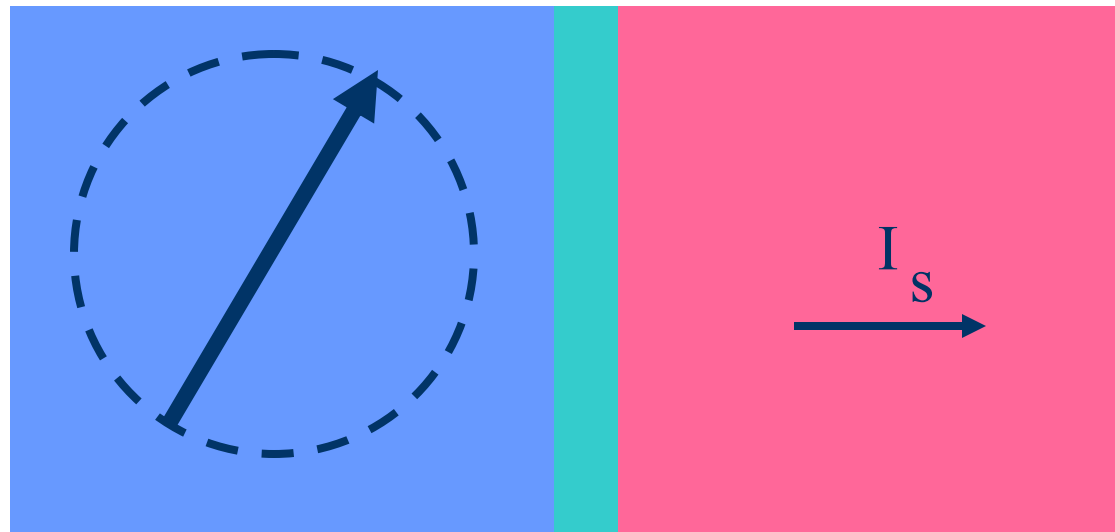
GaAs:  $\tau_s \sim 10^{-7} \text{ s}$  at  $n = 5 \times 10^{16} \text{ cm}^{-3}$

Si:  $l_s \sim$  very long



# Ferromagnetic Resonance

$$\left(\frac{\partial \vec{m}}{\partial t}\right) = -\vec{m} \times H_{\text{eff}} + \alpha \vec{m} \times \frac{\partial \vec{m}}{\partial t}$$



$\alpha$  is enhanced in thin films

$$\alpha = \alpha_0 + \alpha'$$

$$\alpha' = \frac{g_L A_r}{4\pi M}$$

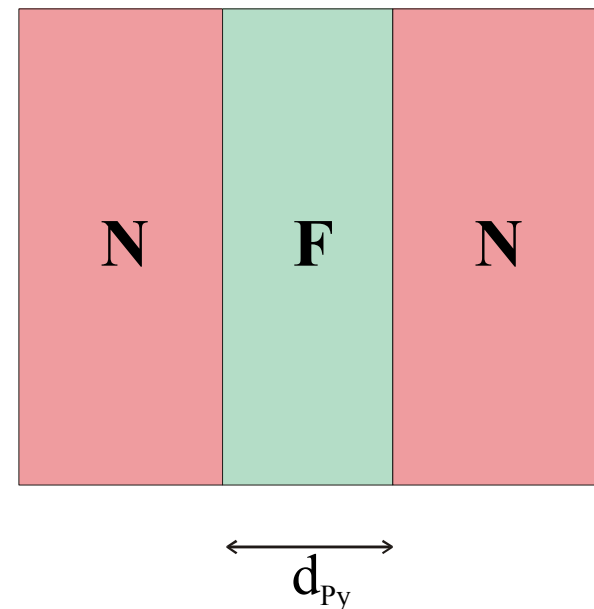
$$A_r = \frac{1}{2} \sum_{nm} \left[ \left| r_{nm}^{\uparrow} - r_{nm}^{\downarrow} \right|^2 + \left| t_{nm}^{\uparrow} - t_{nm}^{\downarrow} \right| \right]$$

# Comparison with Experiments

Exp: S. Mizukami, Y. Ando,  
T. Miyazaki

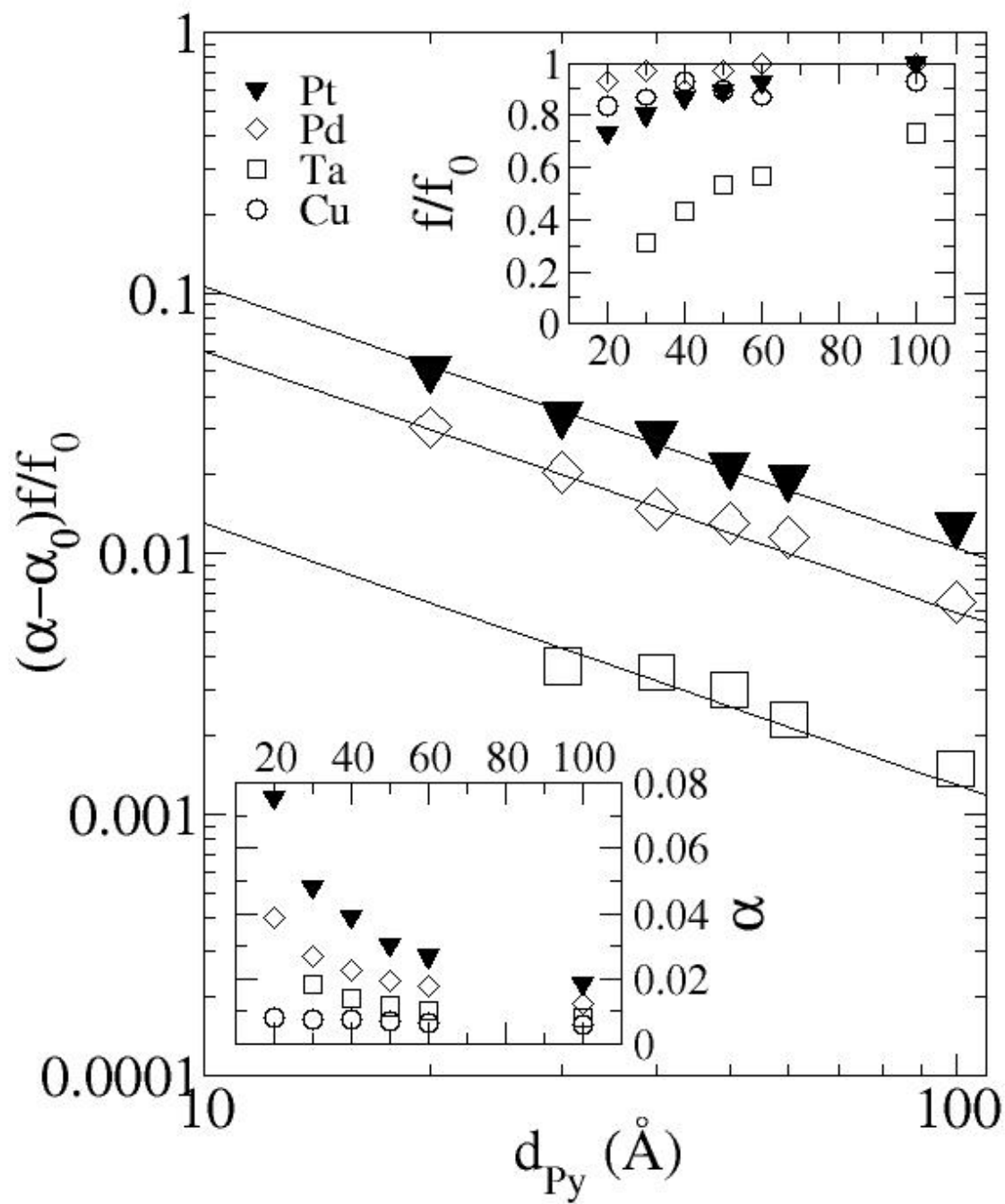
Measure Ferromagnetic Resonance  
Linewidth vs. width of ferromagnet

*Also see experiments by Bret Heinrich et al.*



Our estimate :  $P_y : f = 1.2, g_L = 2.1$

$$\alpha' = 0.3 / d_{Py} (A)$$



# Conclusions

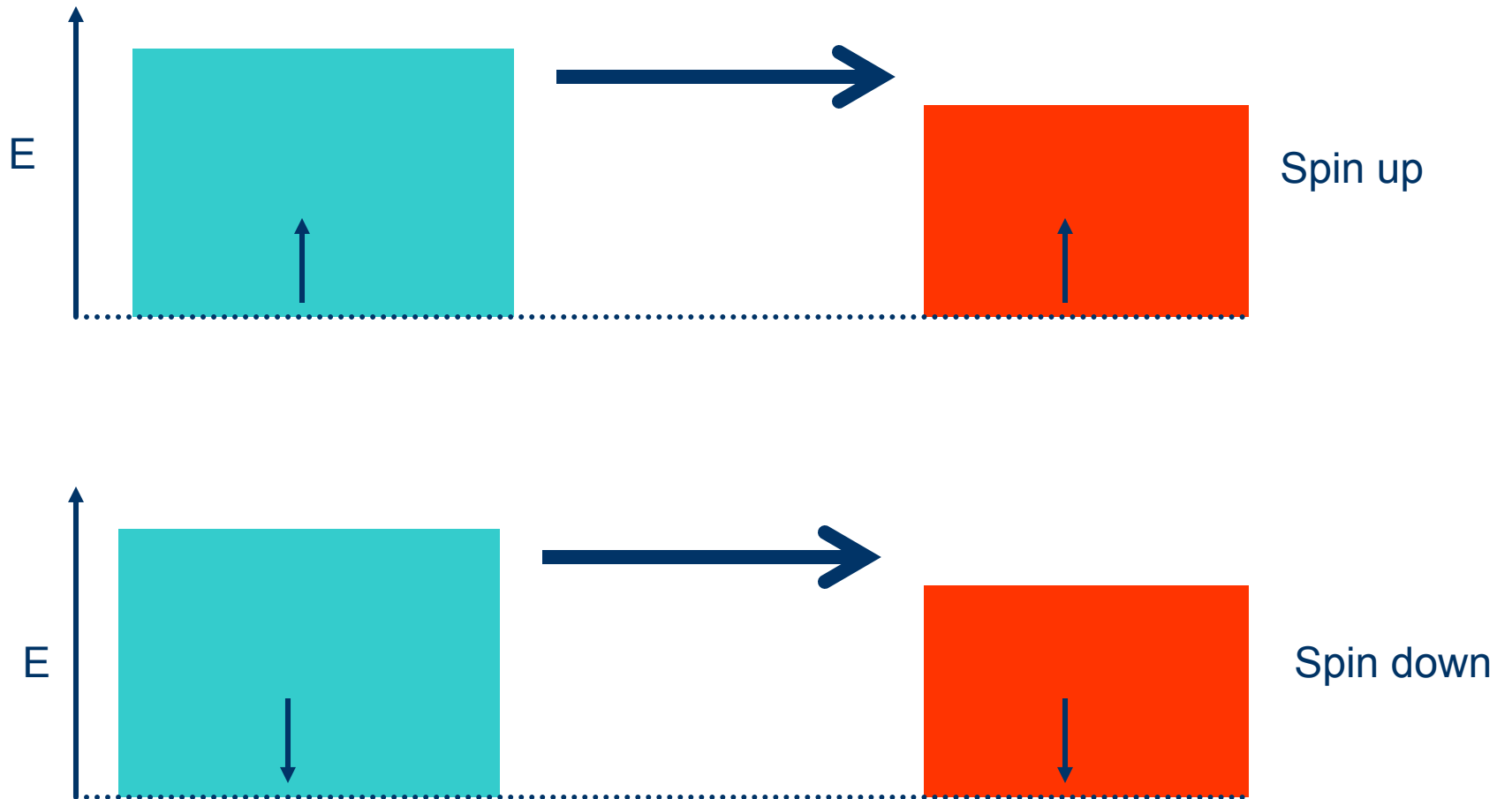
A precessing magnetization emits spin-currents from the ferromagnet into adjacent conductors.

Spin-accumulation when the spin-injection rate is faster than the spin-flip relaxation rate, which is feasible in metals and semiconductors.

Enhanced Gilbert damping when the normal metal is a spin sink.

- Phys. Rev. Lett. **88**, 117601 (2002).
- Phys. Rev. B **65**, 22401(RC) (2002).
- Phys. Rev. B **66**, 060404 (RC) (2002).
- Phys. Rev. Lett **84**, 2481 (2000).

# Charge Battery



# Spin Battery

